Text Diffusion Models, Multimodal LLMs

COMP7607 — Lecture 9

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Generate a sentence

$$p(\boldsymbol{x}) = \prod_{i} p(x_i | \boldsymbol{x}_{< i})$$

Don't just believe that it is because something is trendy that it is ...





LLMs as Agents





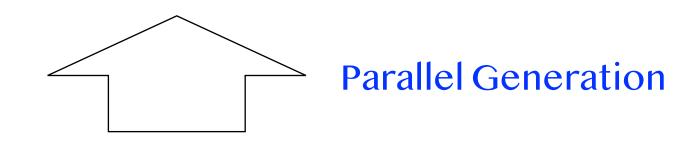
Prompt Engineering

Non-autogressive Text Generation

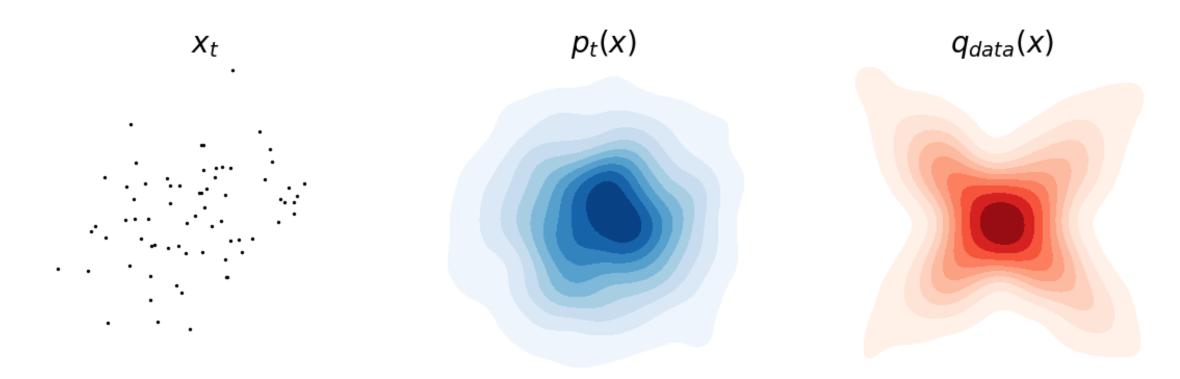
Tokyo is the largest city in the world

Iterative Refinement

Shanghai is the largest city in the world



(mask) (mask) (mask) (mask) (mask) (mask)



In a different "family" of p(x) than the autoregressive ones

4+10 14 14-12 2 <u>13*2=24</u>

1+10-11 13-11=2,7*2=24

3*13-39,9+10-19,39-19-24

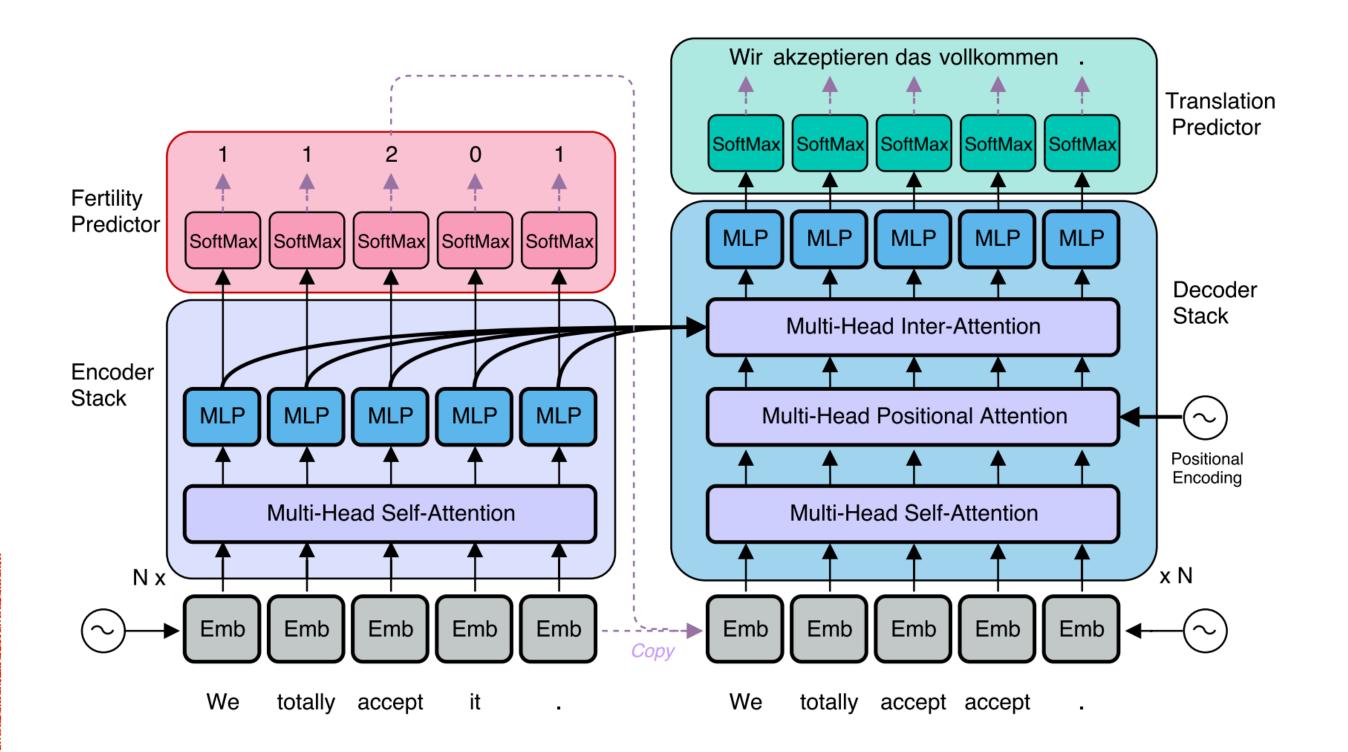
Non-autogressive Neural Machine Translation

Models	WMT14				
	En→De	De→En			
NAT	17.35	20.62			
NAT (+FT)	17.69	21.47			
NAT (+FT + NPD s = 10)	18.66	22.41			
NAT (+FT + NPD $s = 100$)	19.17	23.20			
Autoregressive $(b = 1)$ Autoregressive $(b = 4)$	22.71 23.45	26.39 27.02			

many thanks
thank you

"Modality Conflicts"

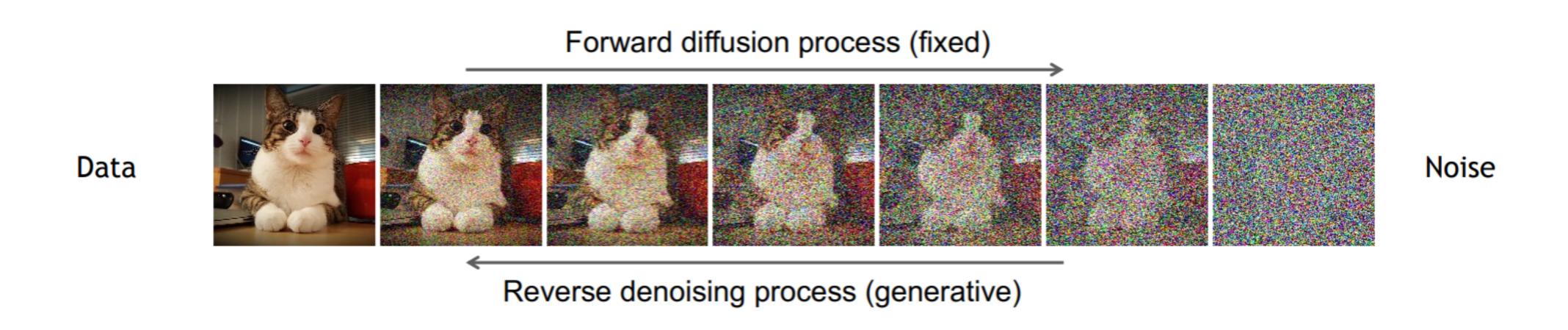
thank thanks



Diffusion Models

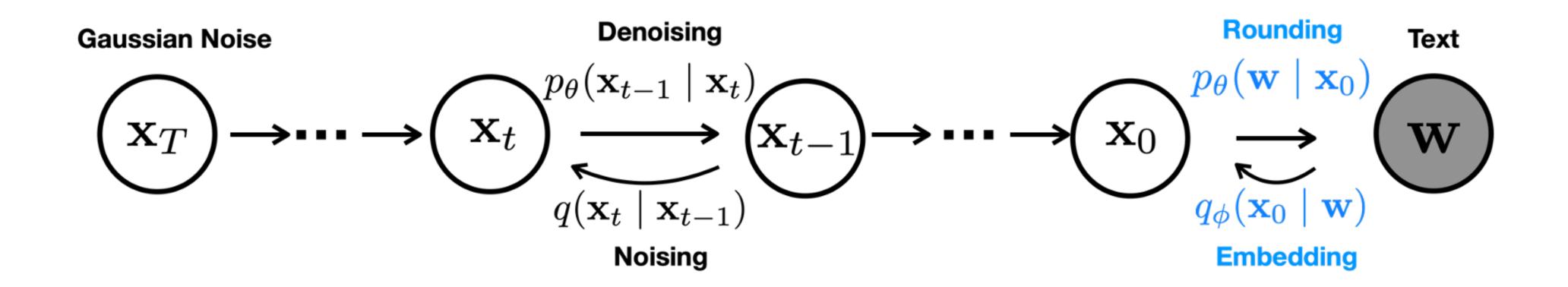
Forward-backward formulation

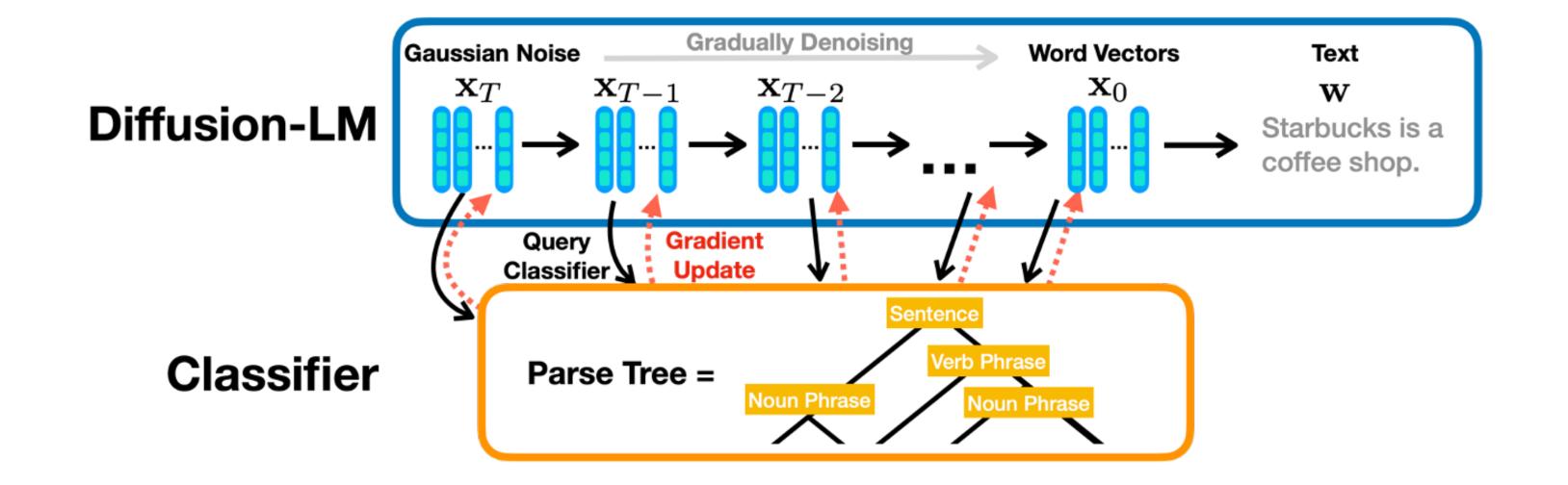
The forward process gradually injects noise to the input The backward process denoises to recover the original data



"Creating noise from data is easy; creating data from noise is generative modeling." (Song et al., 2021)

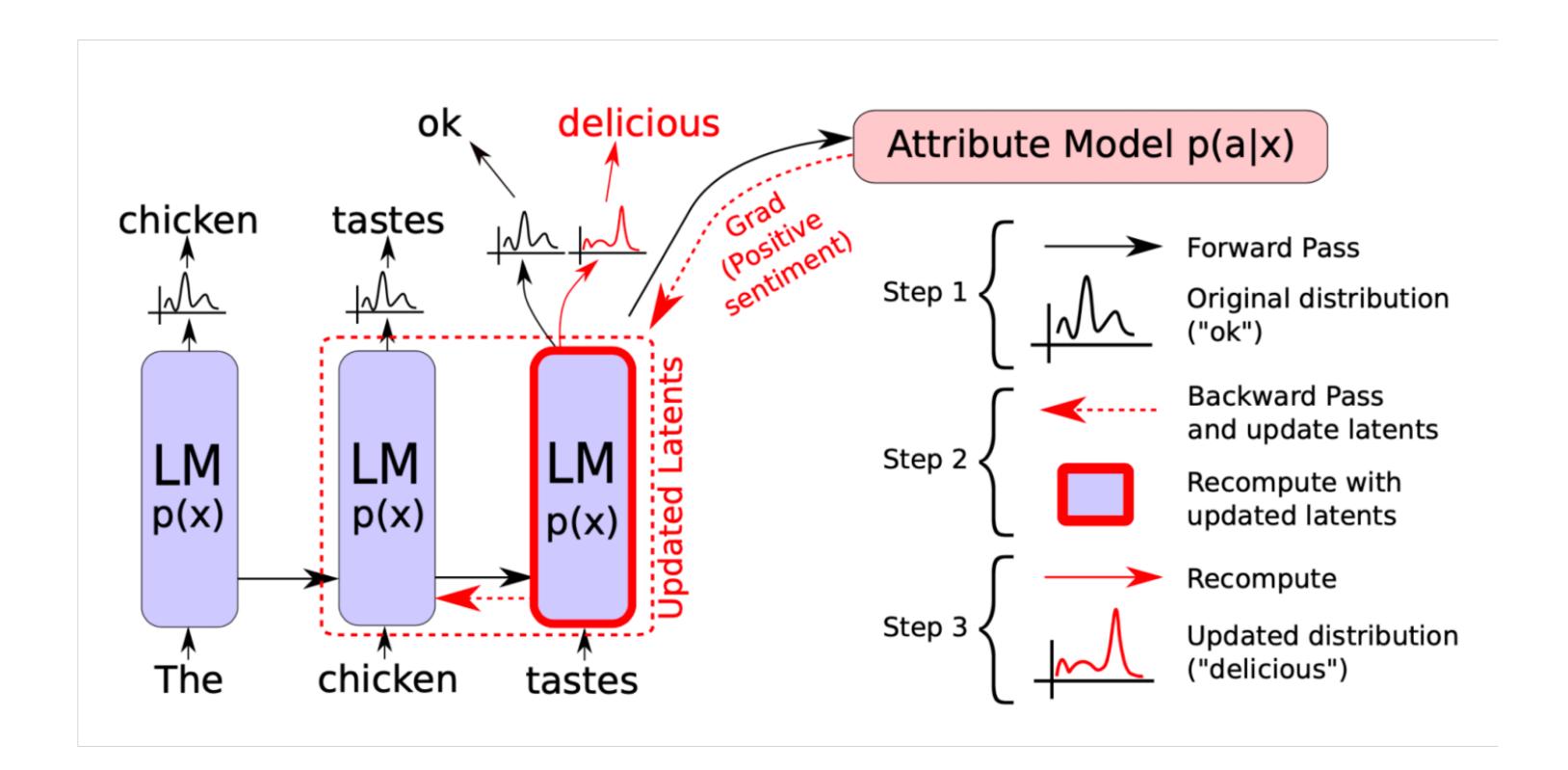
Text Diffusion Models

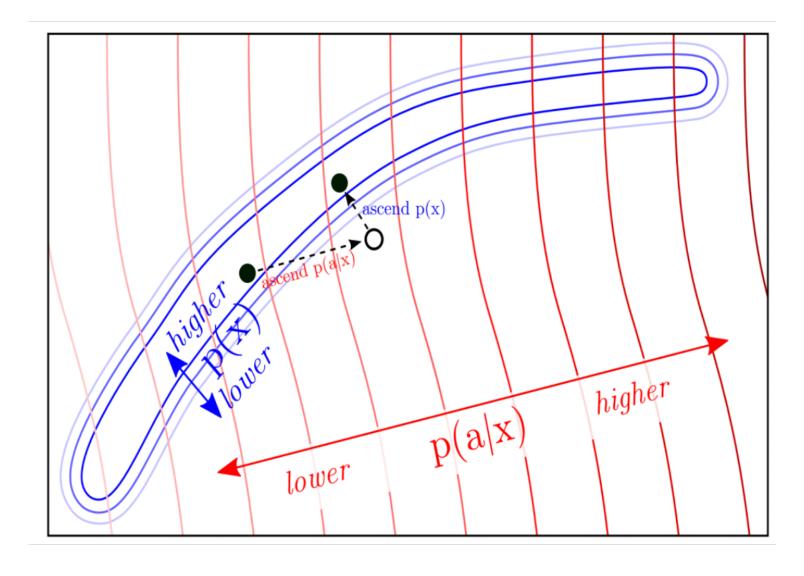




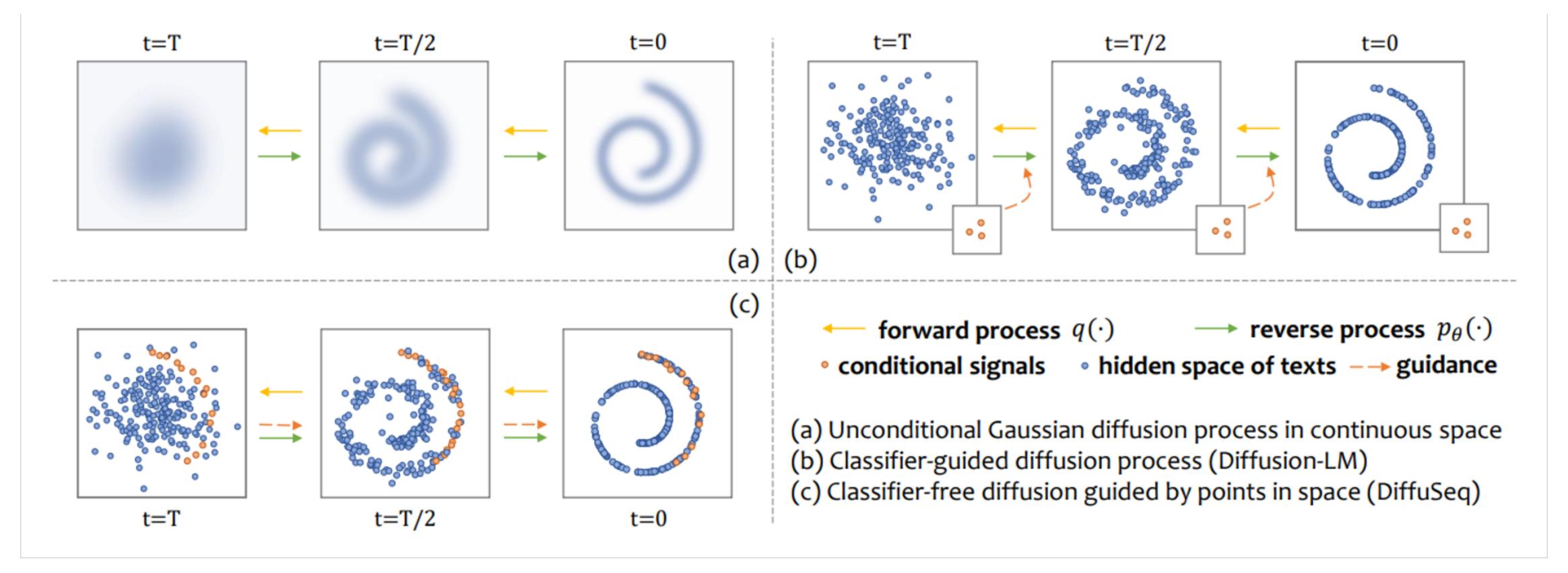


Classifier Guidance



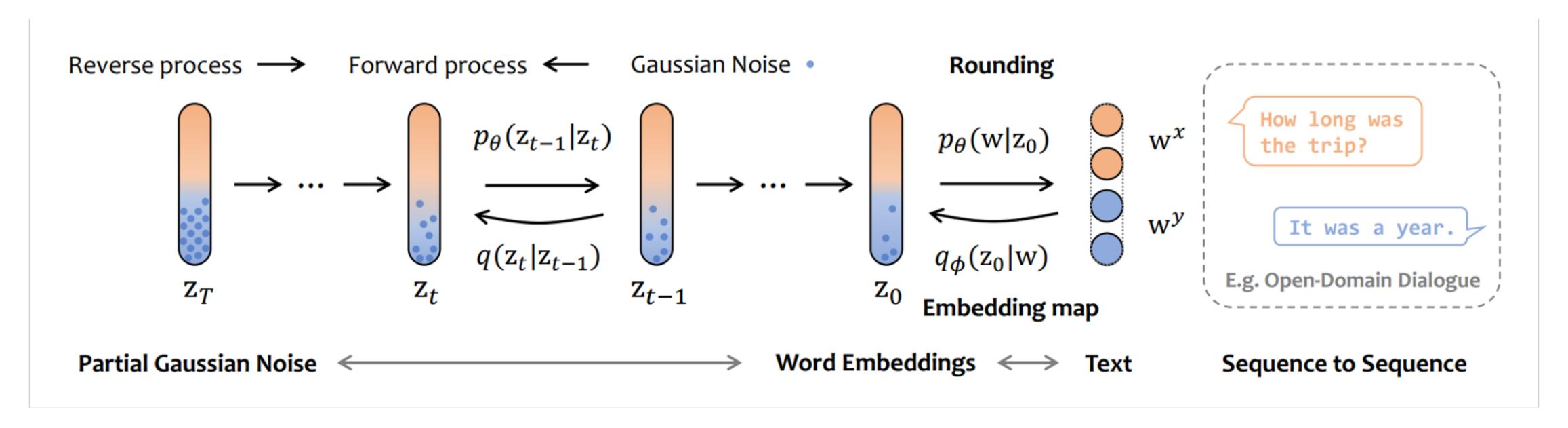


Sequence to Sequence Text Diffusion

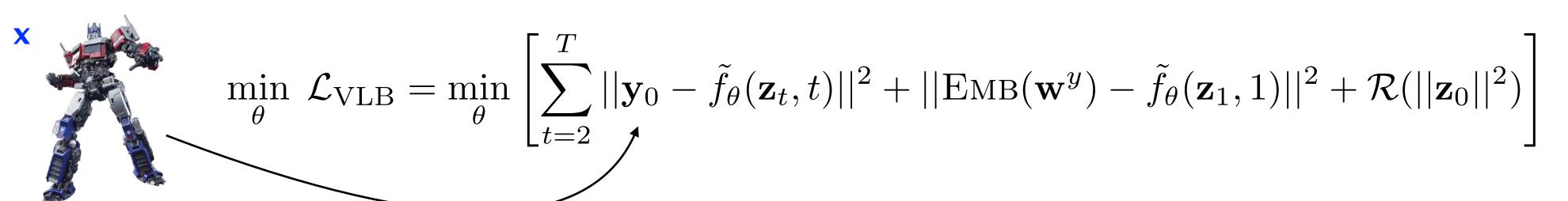


"Seq2Seq" tasks: **x**→**y**

Sequence to Sequence Text Diffusion

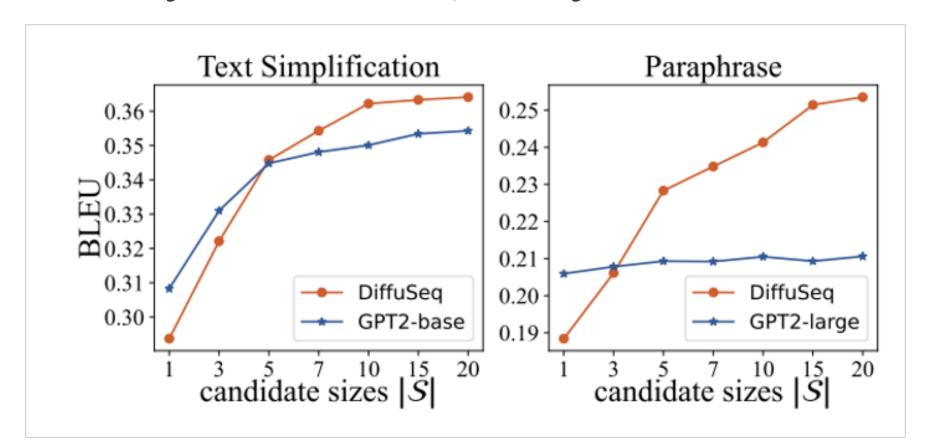


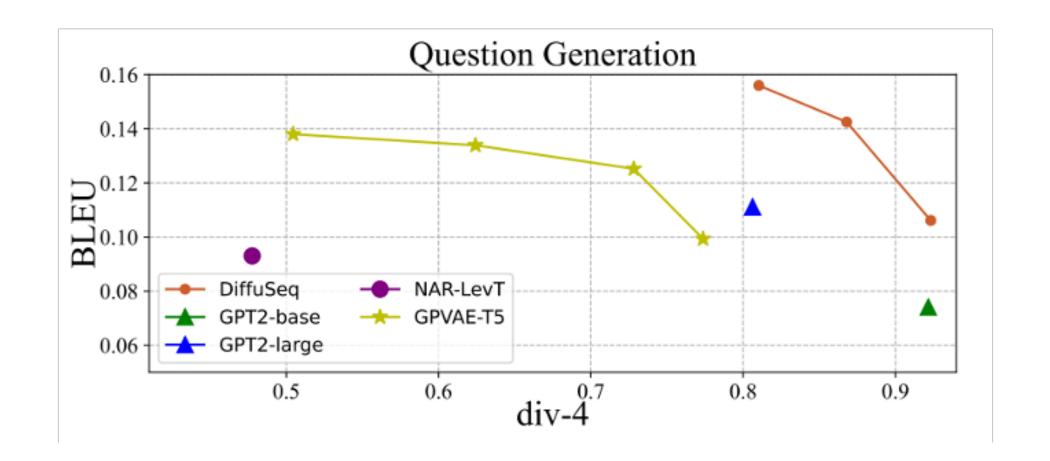
$$\mathcal{L}_{\text{VLB}} = \mathbb{E}_{q(\mathbf{z}_{1:T}|\mathbf{z}_0)} \left[\underbrace{\log \frac{q(\mathbf{z}_T|\mathbf{z}_0)}{p_{\theta}(\mathbf{z}_T)}}_{\mathcal{L}_T} + \sum_{t=2}^{T} \underbrace{\log \frac{q(\mathbf{z}_{t-1}|\mathbf{z}_0, \mathbf{z}_t)}{p_{\theta}(\mathbf{z}_{t-1}|\mathbf{z}_t)}}_{\mathcal{L}_{t-1}} + \underbrace{\log \frac{q_{\phi}(\mathbf{z}_0|\mathbf{w}^{x \oplus y})}{p_{\theta}(\mathbf{z}_0|\mathbf{z}_1)}}_{\mathcal{L}_0} - \underbrace{\log p_{\theta}(\mathbf{w}^{x \oplus y}|\mathbf{z}_0)}_{\mathcal{L}_{\text{round}}} \right]$$



Sequence to Sequence Text Diffusion

Diversity Ensures Quality





Statement: The Japanese yen is the official and only currency recognized in Japan.

Question: What is the Japanese currency?

GPVAE-T5

- * What is the japanese currency
- * What is the japanese currency
- * What is the japanese currency

GPT2-large finetune

- * What is the basic unit of currency for Japan?
- * What is the Japanese currency
- * What is the basic unit of currency for Japan?

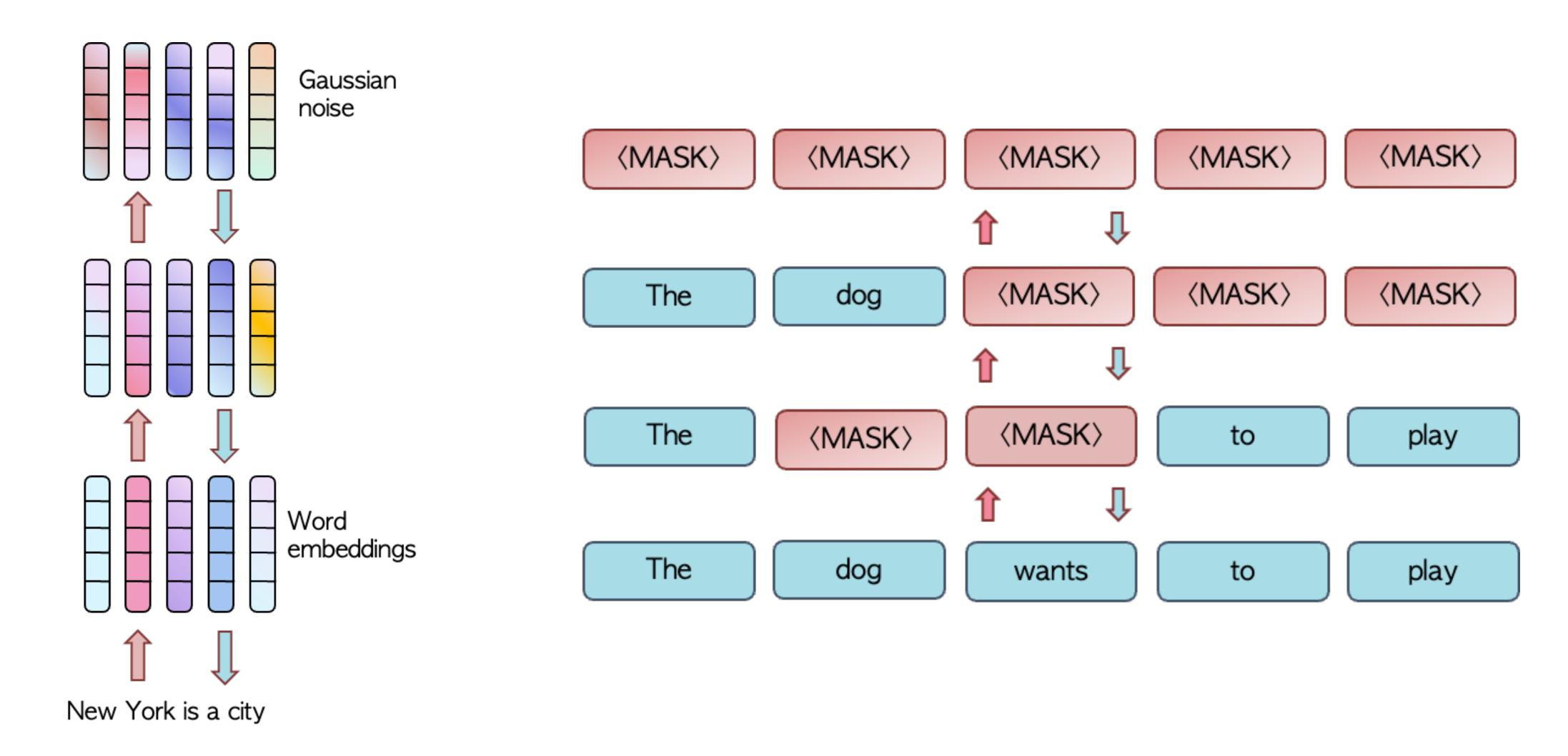
NAR-LevT

- * What is the basic unit of currency for Japan?
- * What is the basic unit of currency for Japan?
- * What is the basic unit of currency for Japan?

DiffuSeq

- * What is the Japanese currency
- * Which country uses the "yen yen" in currency
- * What is the basic unit of currency?

Text Diffusion Models



Discrete Diffusion - Forward Process

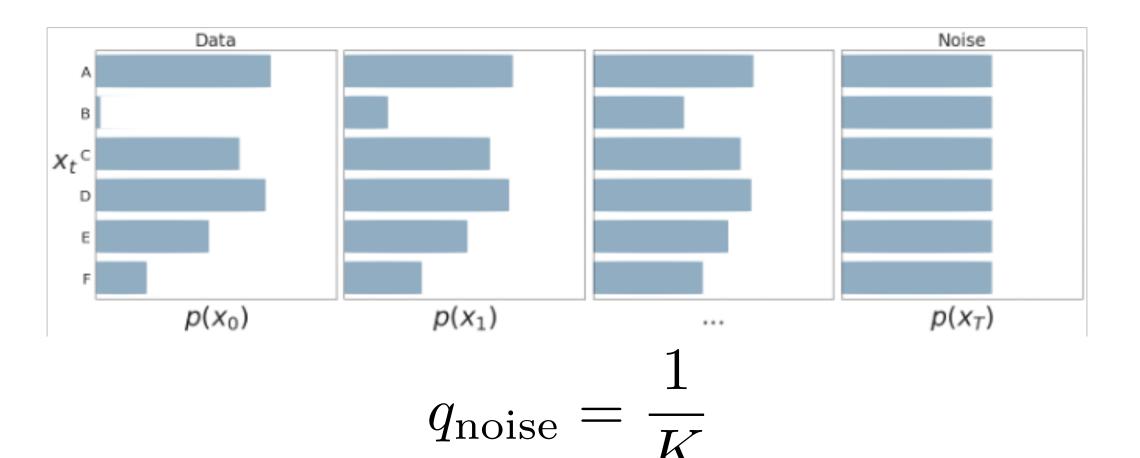
$$q(x_0) = p_{\text{data}}(x)$$

Noise:
$$q(x_t | x_{t-1}) = \beta_t x_{t-1} + (1 - \beta_t) q_{\text{noise}}$$

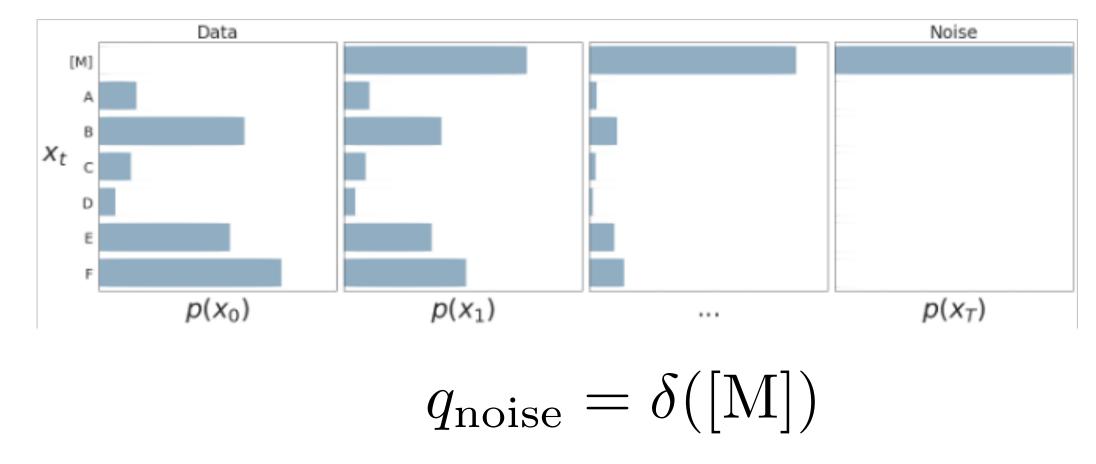
Enjoys closed-form "marginal" distribution:

$$q(\mathbf{x}_t|\mathbf{x}_0) = \alpha_t \mathbf{x}_{t-1} + (1 - \alpha_t)q_{\text{noise}}, \quad \alpha_t \coloneqq \prod_{i=1}^t \beta_i$$

"Multinomial"



"Absorbing"



Discrete Diffusion - Learning

Goal: $p_{\theta}(x_{t-1} \mid x_t) \approx q(x_{t-1} \mid x_t)$

$$\log p_{\boldsymbol{\theta}}(\mathbf{x}_{0}) \geq \mathbb{E}_{q(\mathbf{x}_{1},...,\mathbf{x}_{T}|\mathbf{x}_{0})} \left[\log \frac{p_{\boldsymbol{\theta}}(\mathbf{x}_{0},\mathbf{x}_{1},...,\mathbf{x}_{T})}{q(\mathbf{x}_{1},...,\mathbf{x}_{T}|\mathbf{x}_{0})} \right]$$

$$= \mathbb{E}_{q} \left[\underbrace{\log p_{\boldsymbol{\theta}}(\mathbf{x}_{0}|\mathbf{x}_{1})}_{\mathcal{L}_{1}(\boldsymbol{\theta})} - \sum_{t=2}^{T} \underbrace{\mathrm{KL}(q(\mathbf{x}_{t-1}|\mathbf{x}_{t},\mathbf{x}_{0}) \parallel p_{\boldsymbol{\theta}}(\mathbf{x}_{t-1}|\mathbf{x}_{t}))}_{\mathcal{L}_{t}(\boldsymbol{\theta})} \right] + \text{const.}$$

Enjoys closed-form "marginal" distribution:

"Multinomial"
$$q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0) = \frac{\left(\beta_t \mathbf{x}_t + (1 - \beta_t) \frac{\mathbf{1}}{K}\right) \odot \left(\alpha_{t-1} \mathbf{x}_0 + (1 - \alpha_{t-1}) \frac{\mathbf{1}}{K}\right)}{\mathbf{x}_t^\top \left(\alpha_t \mathbf{x}_0 + (1 - \alpha_t) \frac{\mathbf{1}}{K}\right)}$$
"Absorbing"
$$q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0) = \begin{cases} \mathbf{x}_t, & \text{if } \mathbf{x}_t \neq \mathbf{e}_{[M]}, \\ \frac{1 - \alpha_{t-1}}{1 - \alpha_t} \mathbf{e}_{[M]} + \frac{\alpha_{t-1} - \alpha_t}{1 - \alpha_t} \mathbf{x}_0, & \text{if } \mathbf{x}_t = \mathbf{e}_{[M]} \end{cases}$$

Sampling Reparameterization

Reveals a latent routing mechanism

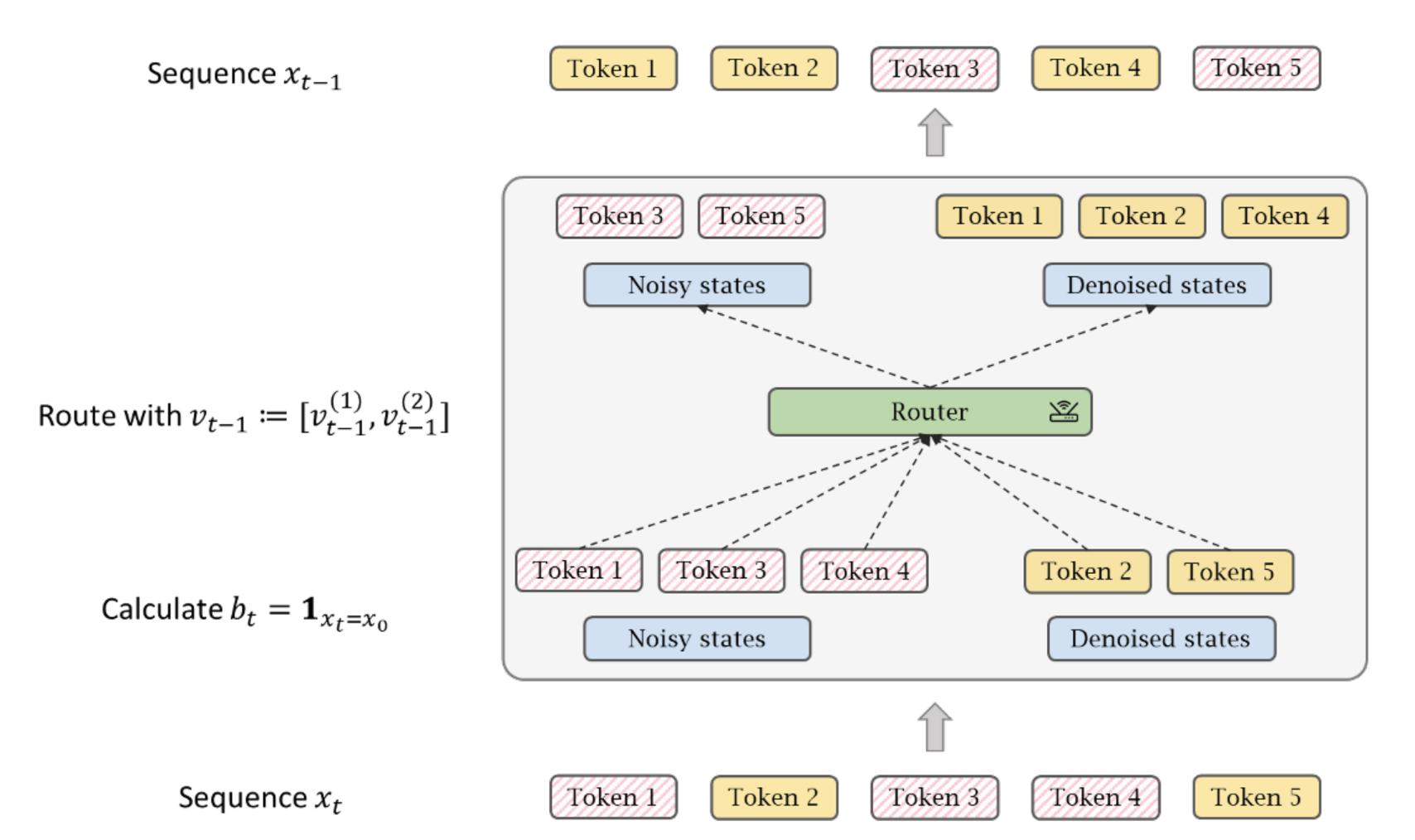
$$b_{t} = \mathbf{1}_{\mathbf{x}_{t} = \mathbf{x}_{0}}$$

$$v_{t-1}^{(1)} \sim \text{Bernoulli}\left(\lambda_{t-1}^{(1)}\right), \quad \mathbf{u}_{t}^{(1)} \sim q_{\text{noise}}$$

$$v_{t-1}^{(2)} \sim \text{Bernoulli}\left(\lambda_{t-1}^{(2)}\right), \quad \mathbf{u}_{t}^{(2)} \sim q_{\text{noise}}(\mathbf{x}_{t})$$

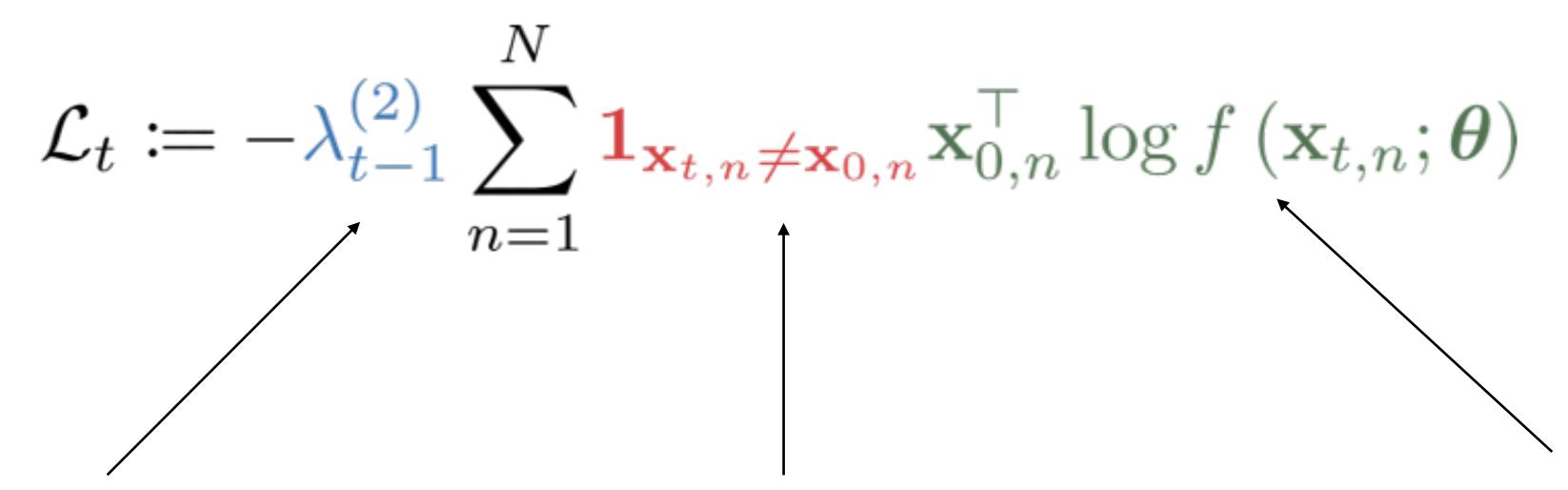
$$\mathbf{x}_{t-1} = b_{t} \left[v_{t-1}^{(1)}\mathbf{x}_{t} + \left(1 - v_{t-1}^{(1)}\right)\mathbf{u}_{t}^{(1)}\right] +$$

$$(1 - b_{t}) \left[v_{t-1}^{(2)}\mathbf{x}_{0} + \left(1 - v_{t-1}^{(2)}\right)\mathbf{u}_{t}^{(2)}\right]$$



Training RDMs

Trained with ELBO:



Evaluated at noisy tokens

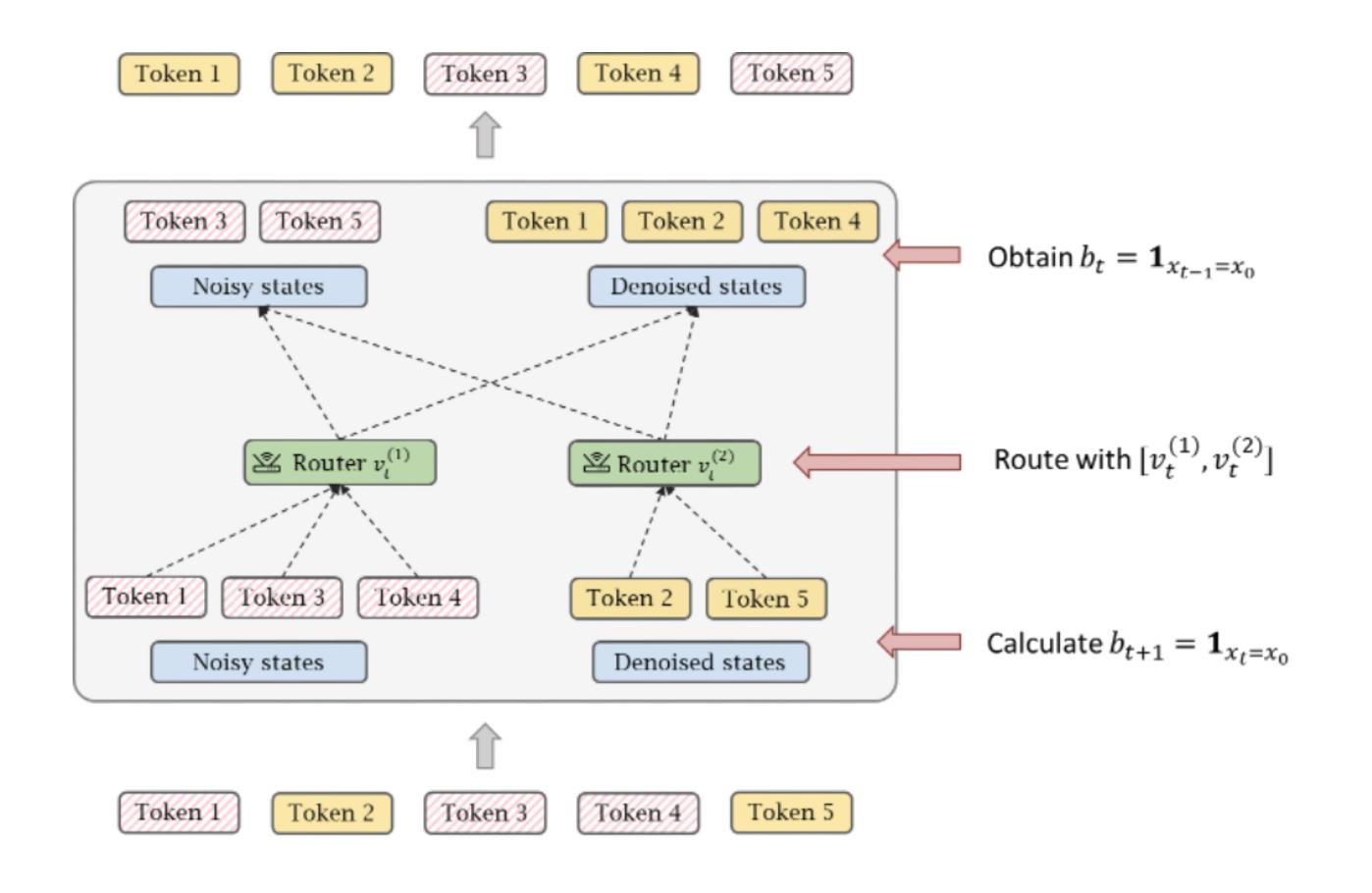
Time-dependent weighting

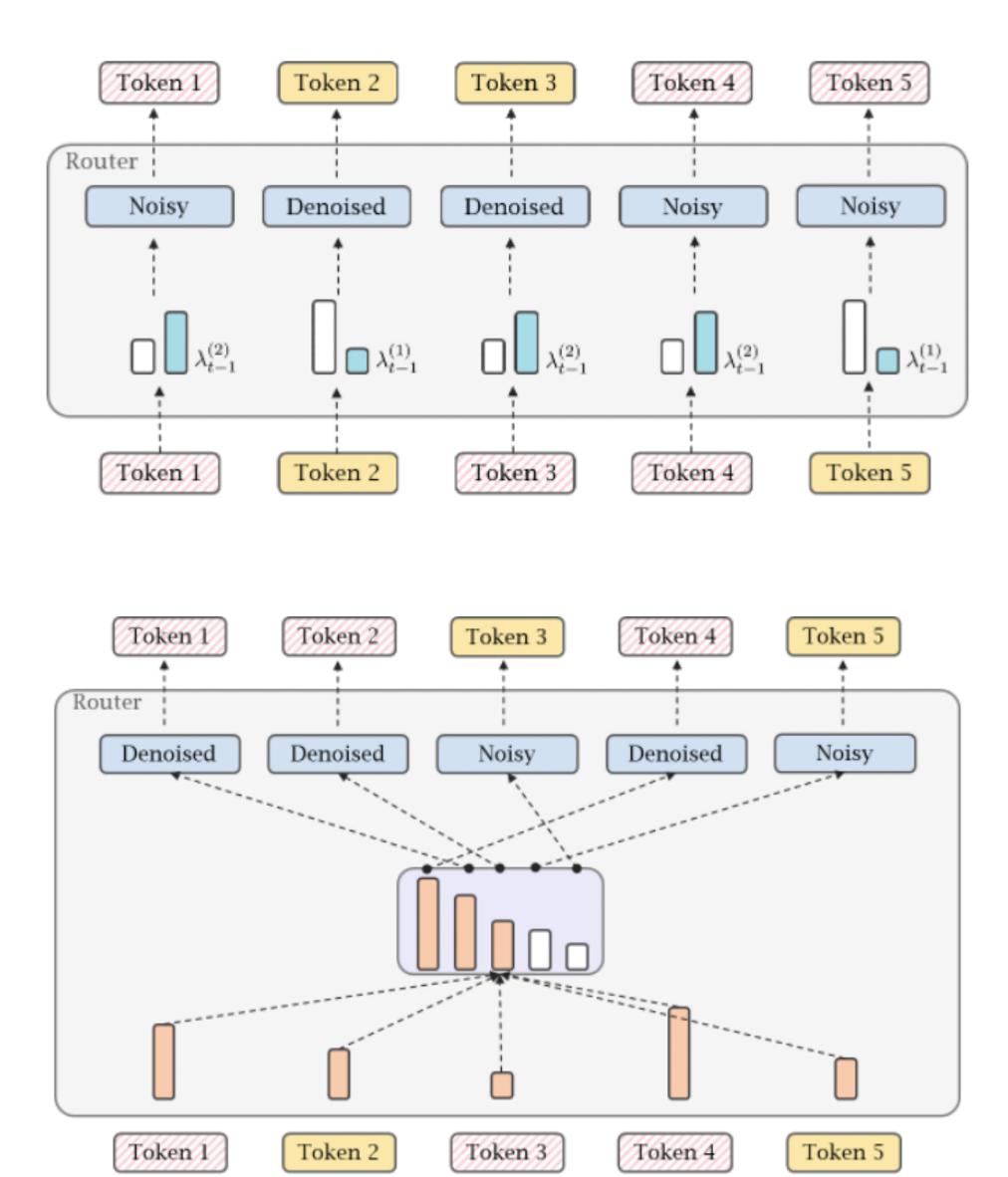
$$\lambda_{t-1}^{(2)} = 1 - \frac{t-1}{T}$$

Router-agnostic

Simple Cross-Entropy Loss

Decoding RDMs





Confident-based Router

Experimental Results of RDMs

Close the gap with autoregressive models (Machine Translation)

	Model	# Iterations	IWSLT: Vanilla	14 DE-EN Reparam.	WMT1 Vanilla	6 EN-RO Reparam.	WMT1	4 EN-DE Reparan
Continuous Diffusion	CDCD (Dieleman et al., 2022)	200		_	_		20.0*	
Discrete Diffusion (Hoogeboom et al.,	Multinomial Diffusion (Hoogeboom et al., 2021)	2	23.05	28.01	26.61	30.16	4.28	21.43
		4	24.24	30.57	27.81	31.70	4.31	24.05
		10	21.28	32.23	25.25	33.00	6.94	25.63
		16	20.59	32.58	24.36	33.11	6.07	25.64
		25	20.06	32.84	23.94	33.31	3.69	26.04
	Absorbing Diffusion	2	25.24	27.60	27.24	30.72	16.46	21.00
		4	26.93	31.47	29.16	32.60	19.48	24.26
		10	28.32	33.91	30.41	33.38	21.62	26.96
	(Austin et al., 2021)	16	28.38	34.41	30.79	33.82	22.07	27.58
		25	28.93	34.49	30.56	33.99	22.52	27.59
Auto-regressive Models	Transformer-base (Vaswani et al., 2017)	n.a.	3	4.51	3	4.16	2	7.53

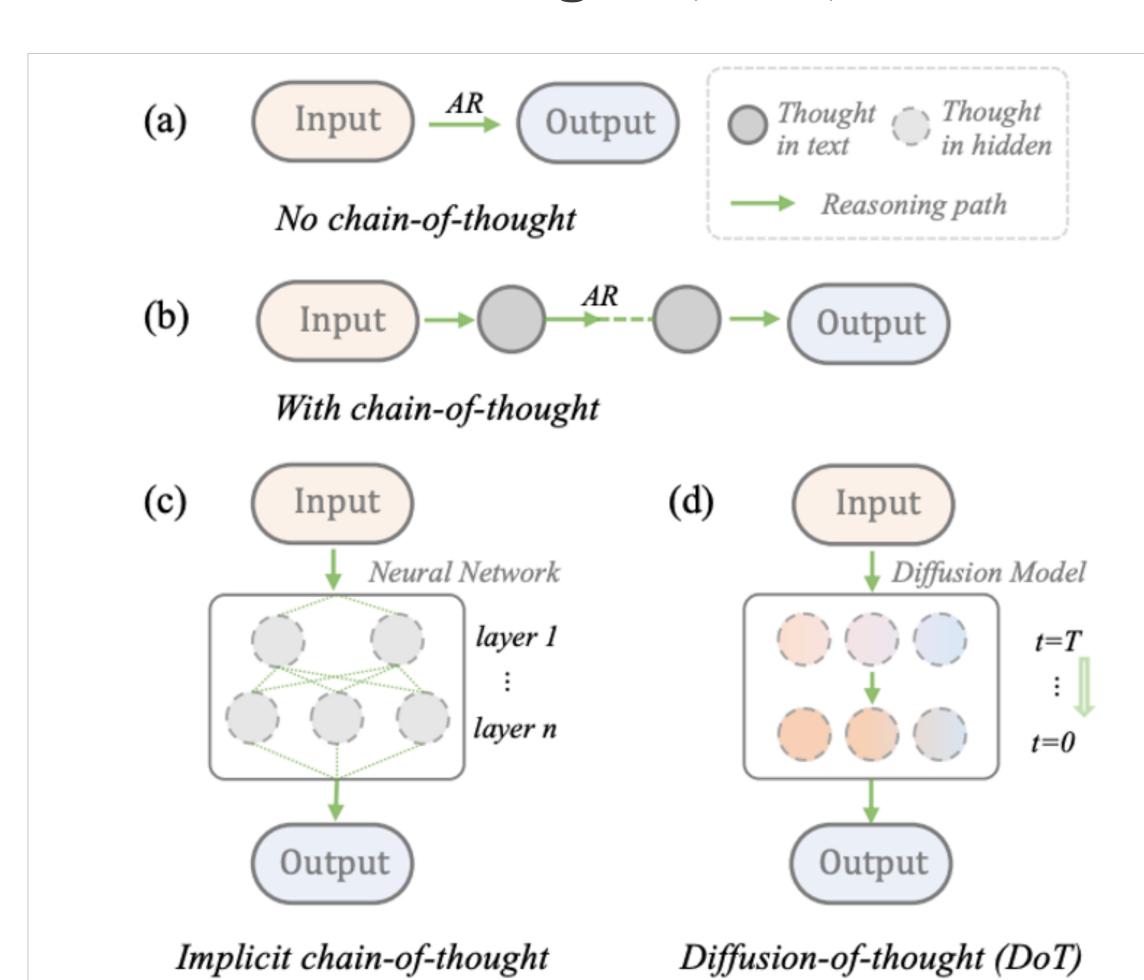
Experimental Results of RDMs

Fix previously made errors in where vanilla discrete diffusion models get stuck

Source: i have only 2 months for my ca cpt exams how do i prepare? **Reference:** i want to crack ca cpt in 2 months. how should i study? # Iter. Decodes Absorbing \circ <M> <M> <M> <M> ca - ca cp <M> ca <M> <M> exam <M> \circ <M> can <M> prepare <M> ca - ca cp <M> ca <M> ##t exam ? o how can i prepare for ca - ca cp ##t ca cp ##t exam ? DM-absorbing \circ how <M> i <math><M> <M> <math><M> <M> <math><M> <M> <math><M> <M> <math><M> <math>< \circ how <M> i prepare for ca <M> ##t <math><M> <math><M> <math><M> <math><M> <math><M> ?o how <M> i prepare for ca cp ##t <M> <M> months months ? o how <M> i prepare for ca cp ##t exam in two months <M> ? o how can i prepare for ca cp ##t exam in two months left ?

Autoregressive LLMs, what else?

Diffusion of Thoughts (DoTs)





Questions:

When Freda cooks canned tomatoes into sauce, they lose half their volume. Each 16 ounce can of tomatoes that she uses contains three tomatoes. Freda's last batch of tomato sauce made 32 ounces of sauce.

How many tomatoes did Freda use?

```
© CoT Decoding:

O DoT Decoding:

<<32/16=2>> <<12/12=2*3 ## *2=2= #####

MP-DoT Decoding:

<<32===2>>
```

Mutilmodal LLMs

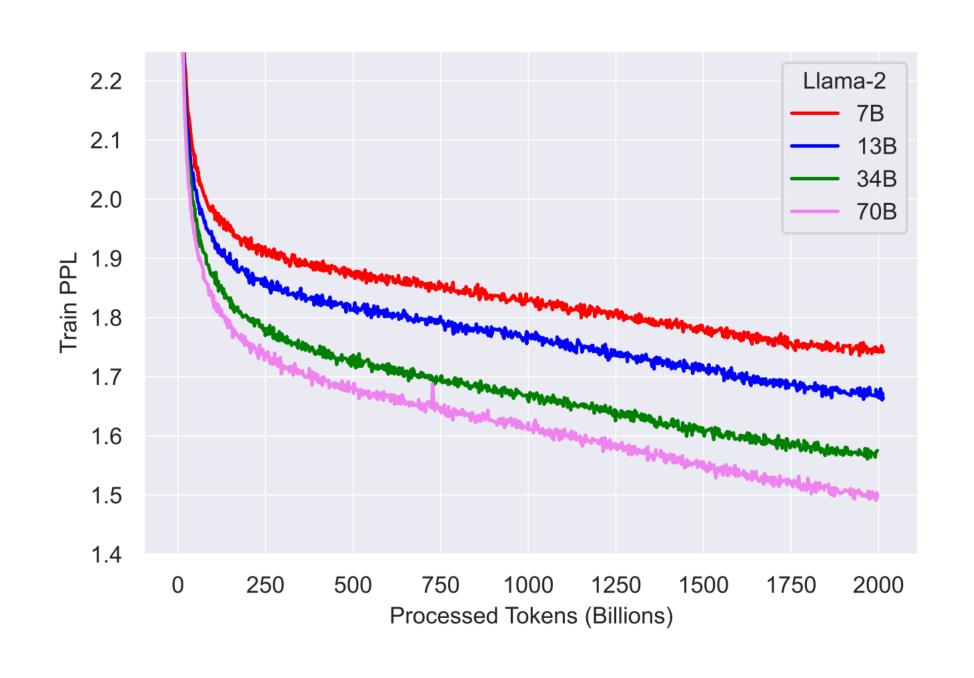
- Motivation: Why do we need a versatile large multimodal models (LMMs)?
- Progress: What recipe do we have for building capable LMMs?
 - Architecture
 - Data
 - Training Recipe

Future Directions: What we can do in the area of LMMs?



Motivations: Why LLMs

Compression of AGI



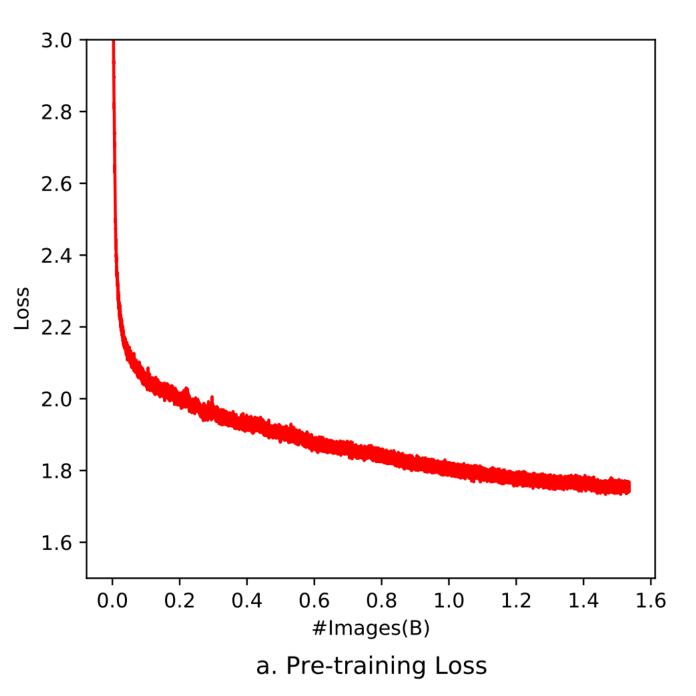


Image = 256 tokens Caption ~= 64 tokens

 $\sim 500B$ tokens $\rightarrow \sim 1.8$

LLaMA-2-7B 500B tokens -> 1.9

LLaMa-2 Training Loss

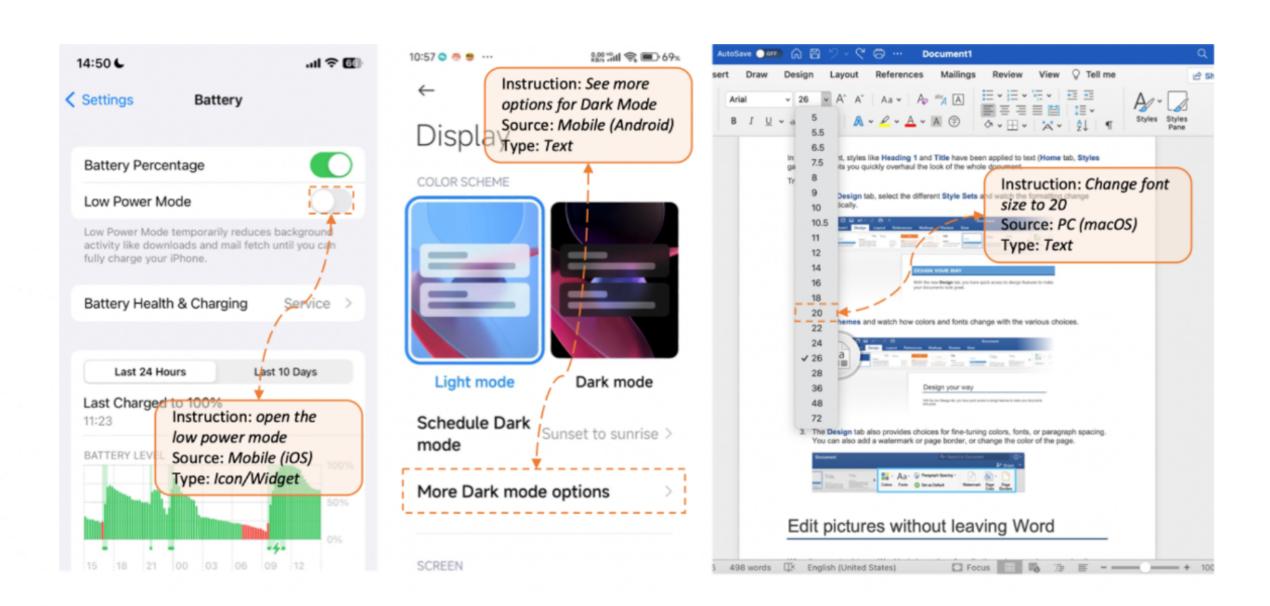
Qwen-VL-Chat (7B)

Motivations: Why LLMs

Real-world applications are beyond text.





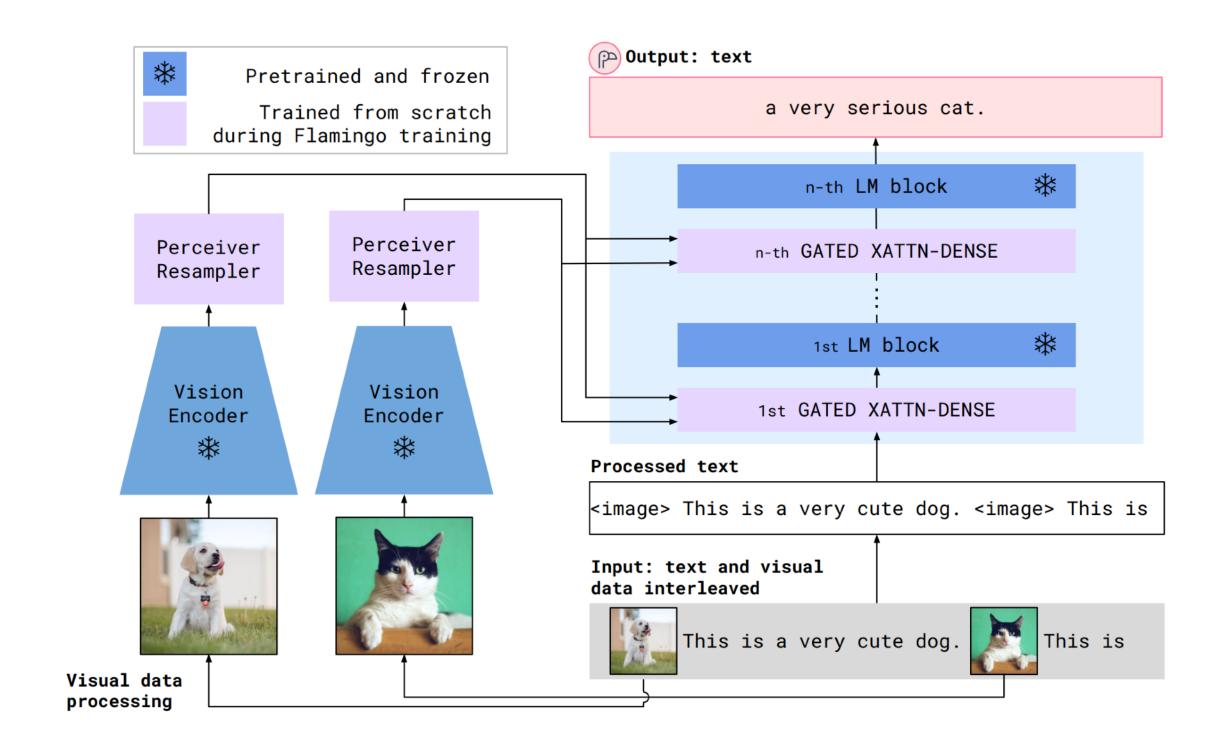


Embodied Robot

GUIAgent

RT-2: New model translates vision and language into action SeeClick: Harnessing GUI Grounding for Advanced Visual GUI Agents

Architecture Overview



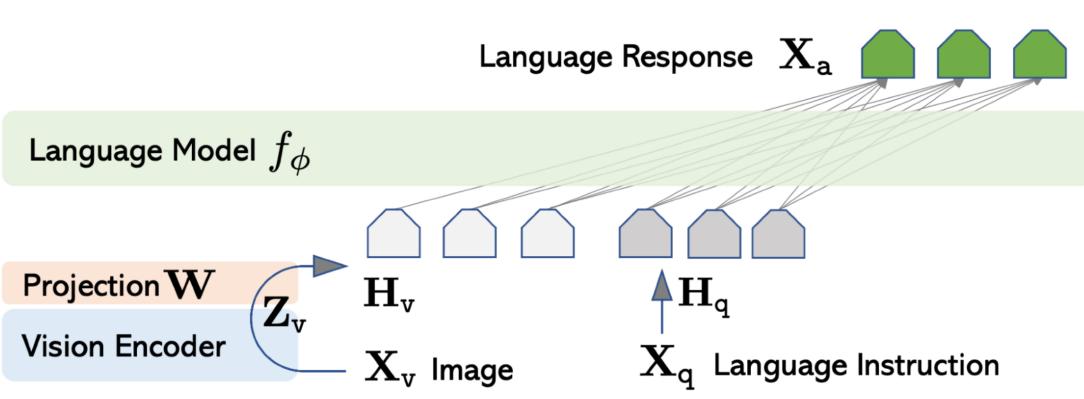


Figure 1: LLaVA network architecture.

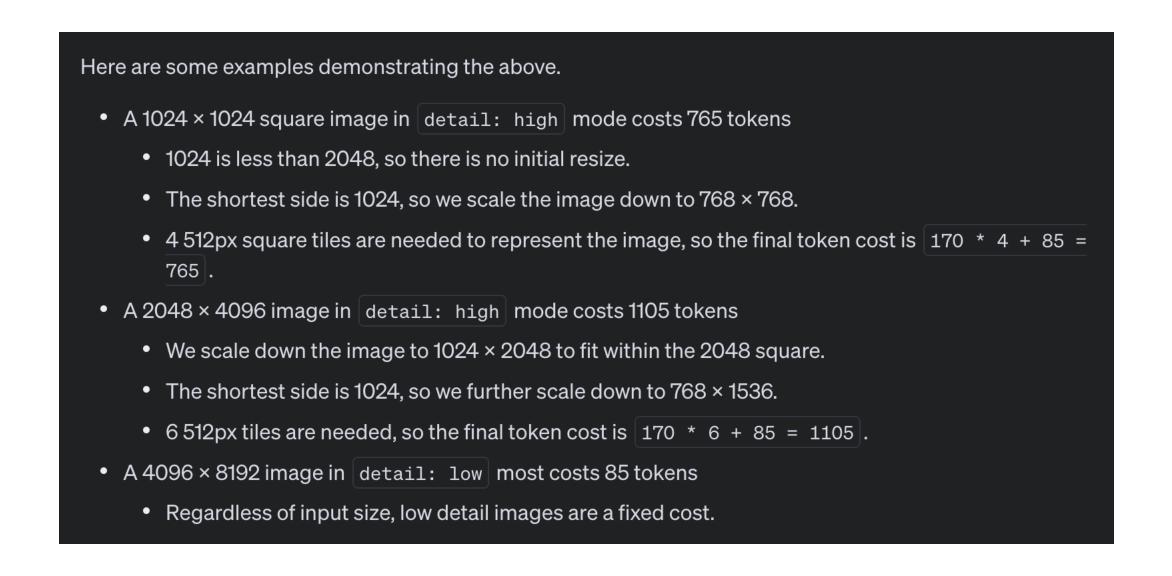
Flamingo
Images are integrated via
Gated Cross-Attention

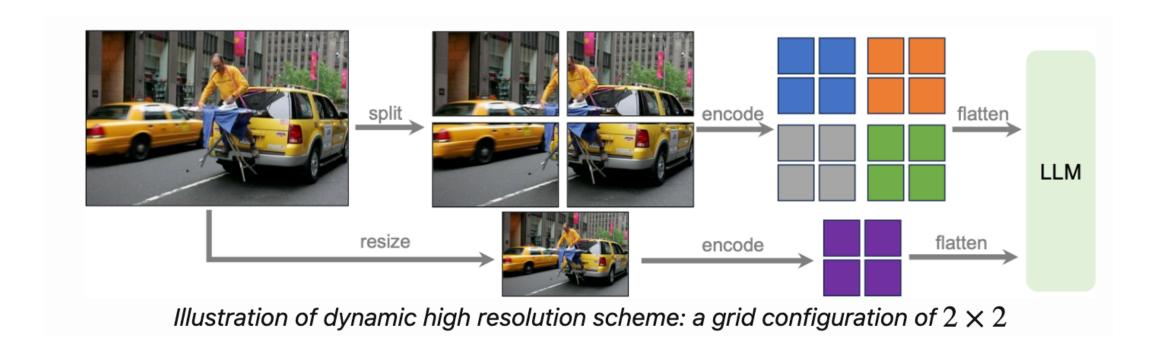
LLaVA / Qwen-VL-Chat / MiniGPT4 ..
Images are treated as Word Embeddings
More prevailing now

Architecture Design Space

- Large Language Model:
 - O Use the best LLM available.
- Vision Encoder:
 - Influence of the image resolution.
 - O Which vision encoder shall we use?
- Modality Projector:
 - O How to effectively represent the image in word embedding space?

How might GPT-4v deal with high resolution?

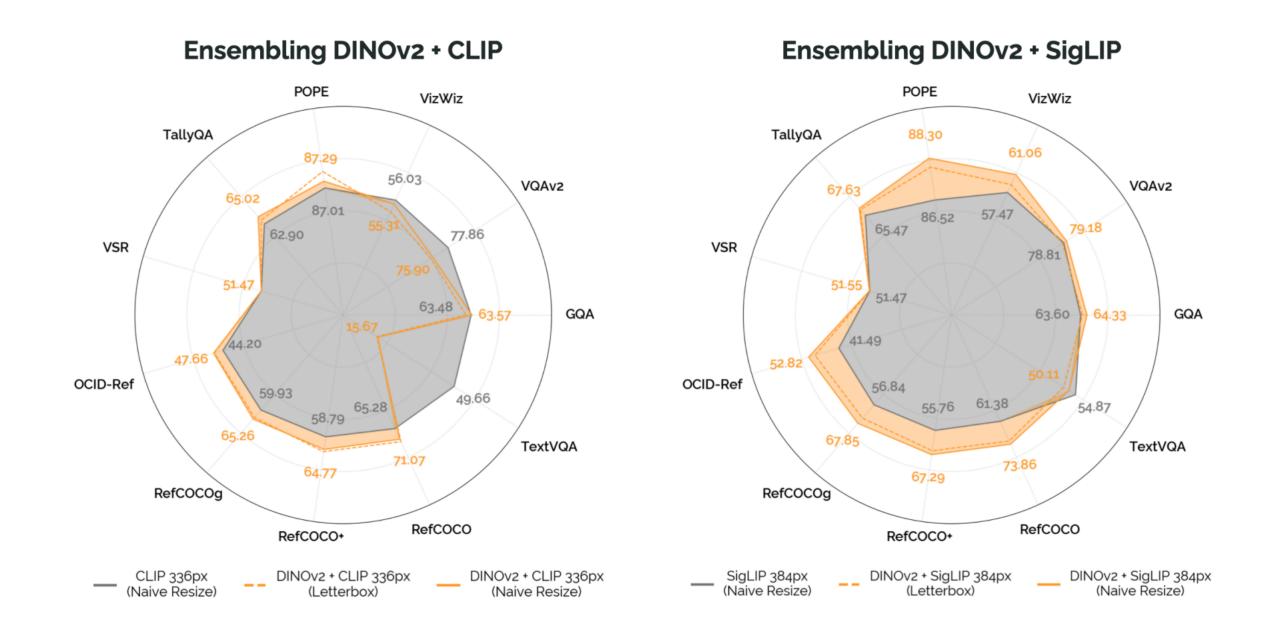




GPT-4V Document

LLaVA-Next cuts image into grids to reduce the computation overhead

Vision Feature Types



- Single CLIP Feautre is not comprehensive for grounding related tasks.
- Combination of SigCLIP and DINOv2 (image SSL) leads to the best results across benchmarks.

GPT-4V Document

Modality Projector

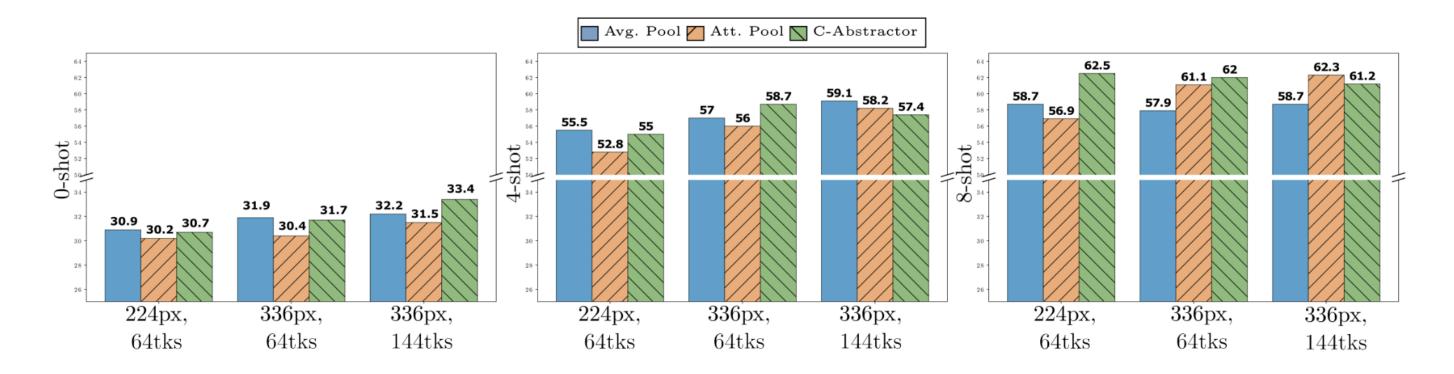
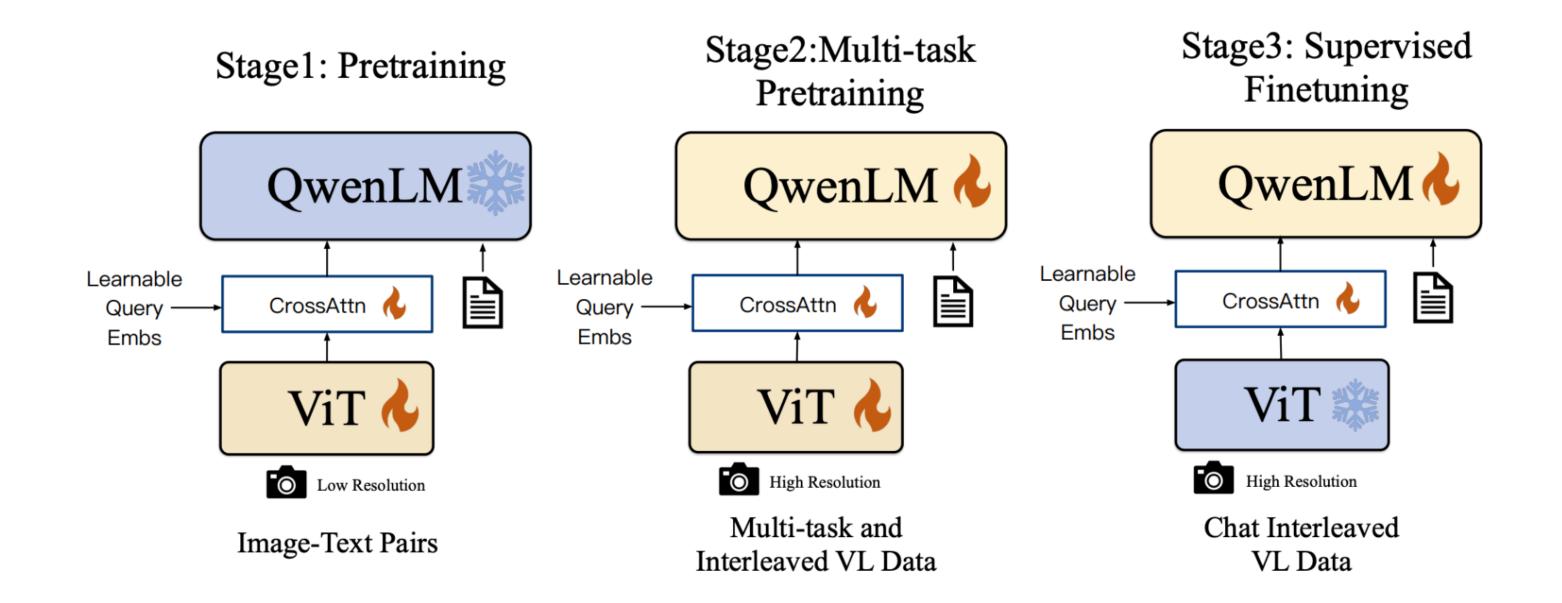


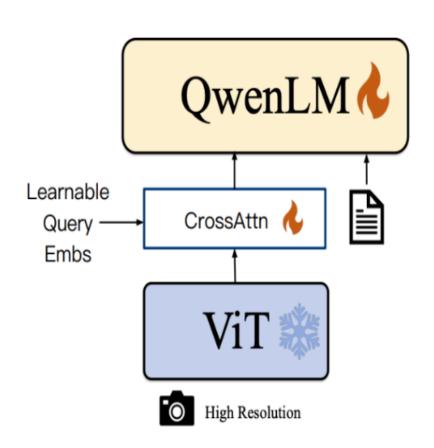
Fig. 4: 0-shot, 4-shot, and 8-shot ablations across different visual-language connectors for two image resolutions, and two image token sizes.

- Projector can be utilized to compress the visual tokens as well, which one shall we use?
- Avg Pooling v.s. Attn Pooling v.s C-Abstractor (ResNet Pooling)
- Findings:
 - Number of visual tokens and image resolution matters most, while the type of VL connector has little effect.

Data & Training Stage Overview



Stage 4: Alignment according to Feedback



VL Feedback data

General VL Datasets

- Stage 1: Large-scale Paired dataset for modality alignment
 - Scale & Quality
 - Raw datasets: Laion5B, Datacomp-1B
 - LLM (LMMs) rewrites dataset: Laion-COCO,
 Capsfusion, ShareGPT4V
- Stage 2 & 3: Instruction tuning datasets / Chatty
 Dataset
 - M3IT (Academic VL tasks, https://m3-it.github.io), wide coverage.
 - LLaVA-Instruct (GPT-4/ChatGPT generated psuedomutlimodal dataset)
 - Specialized Domain Datasets: AI2D, OCR-VQA, LLaVAR, ChartVQA, G-LLaVA



COCO: Young children standing on a platform waiting for a train to arrive. Adults and children watching a train slowly leave.

A family near a railroad track watching the train pass.

People waiting on a platform as a train pulls up.

A train station with a green chain on the tracks and children waiting for it to go by.

LLaVA: At a train station, a group of people, including both young children and adults, are standing on a platform waiting for a train to arrive. The train is already present on the tracks, partially visible on the right side of the image. Some of the people watch the train closely, while others seem to be patiently anticipating its departure.

There is a total of eight individuals waiting for the train, with one child in the middle of the platform and the others scattered around. A backpack can be found on the far left side of the platform, suggesting that someone may have set it down while waiting.

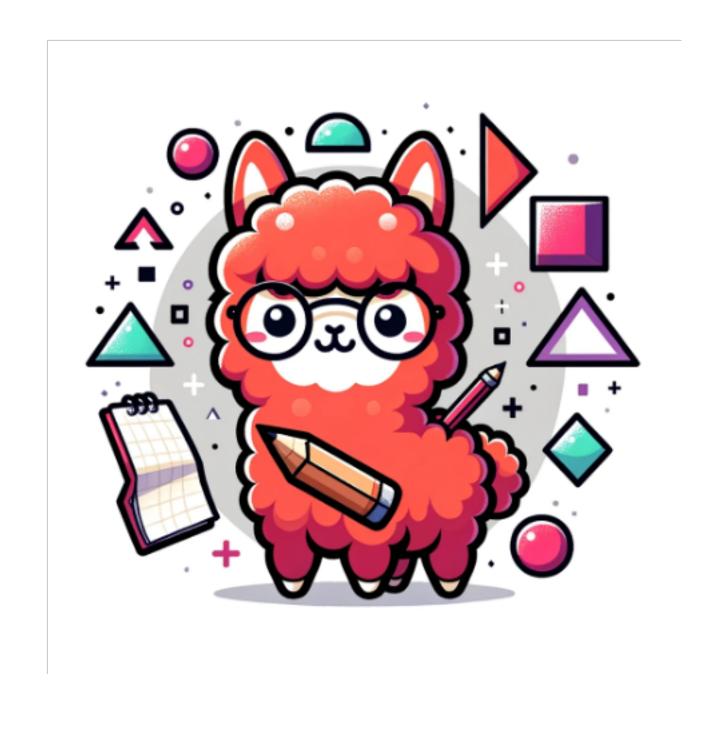
ShareGPT4V: The image captures a moment at a train station. A green train is on the tracks, moving away from the platform labeled "Platform 2". The train's motion is observed by people standing on the platform, their attention drawn to the departing vehicle.

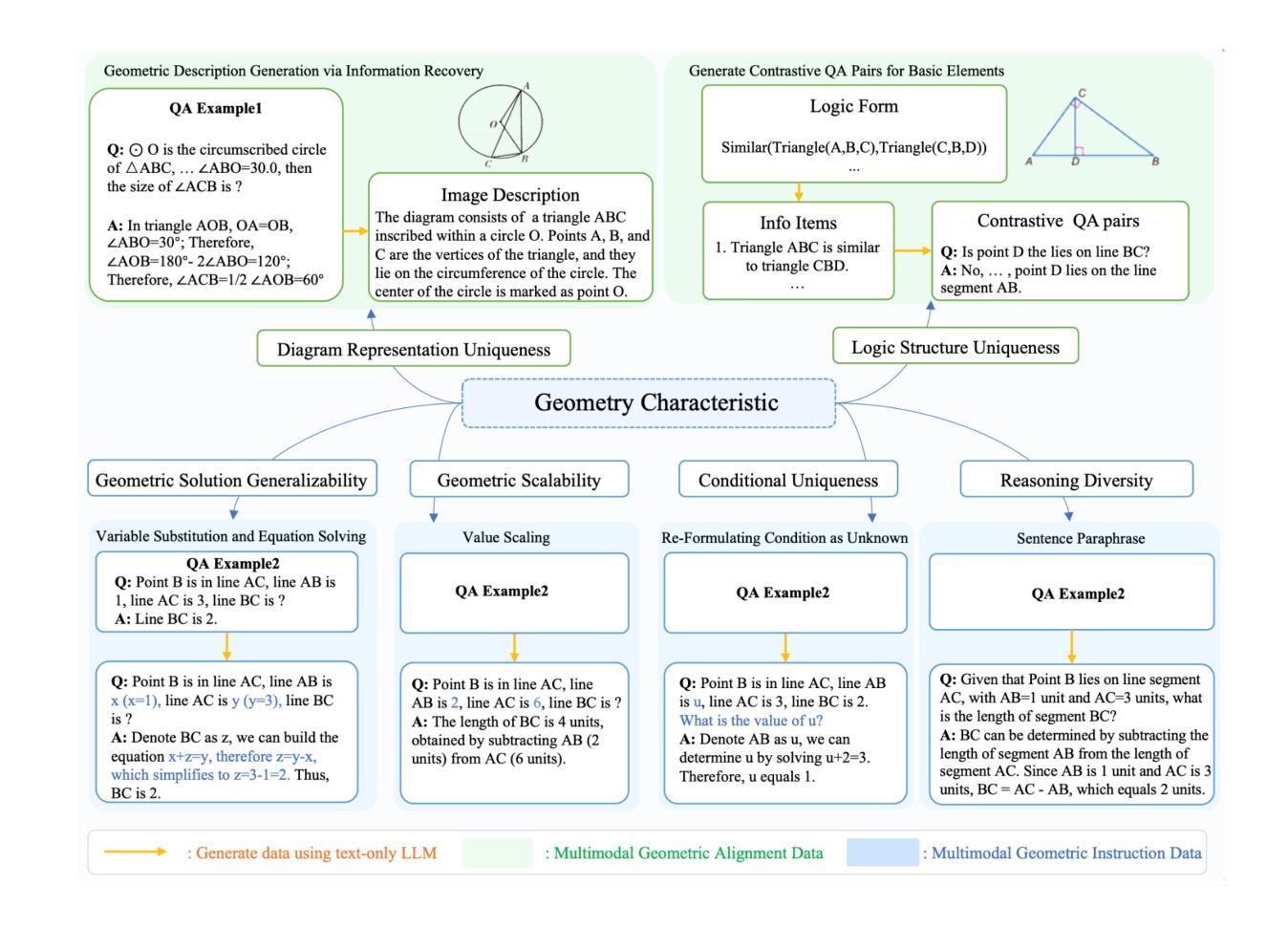
A red signal stands on the tracks, its vibrant color contrasting with the green of the train. Signs are prominently displayed around the platform. One warns "Beware of Trains", a cautionary reminder of the powerful machines that frequent these tracks. Another sign advises "Please Use The Footbridge To Cross The Line. If You Require Assistance Please Ask The Station Staff", guiding passengers to safely navigate the station.

The sky above is a clear blue, providing a serene backdrop to the bustling activity of the station. In the distance, trees can be seen, adding a touch of nature to this man-made setting. The image is a snapshot of everyday life at a train station, capturing both its routine operations and its inherent charm.

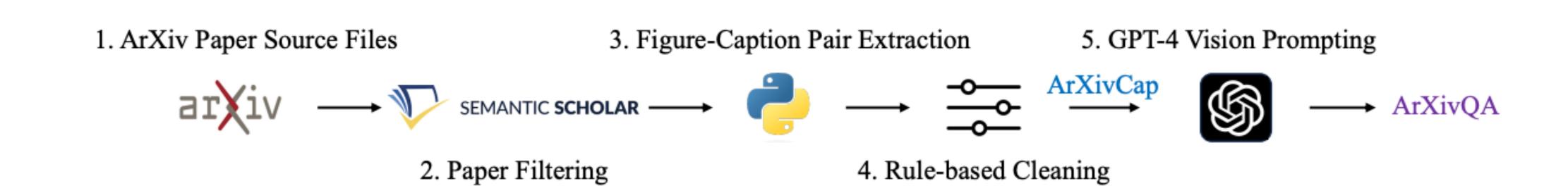
(a) Comparison of Captions' Quality

Datasets for LLMs Math Reasoning





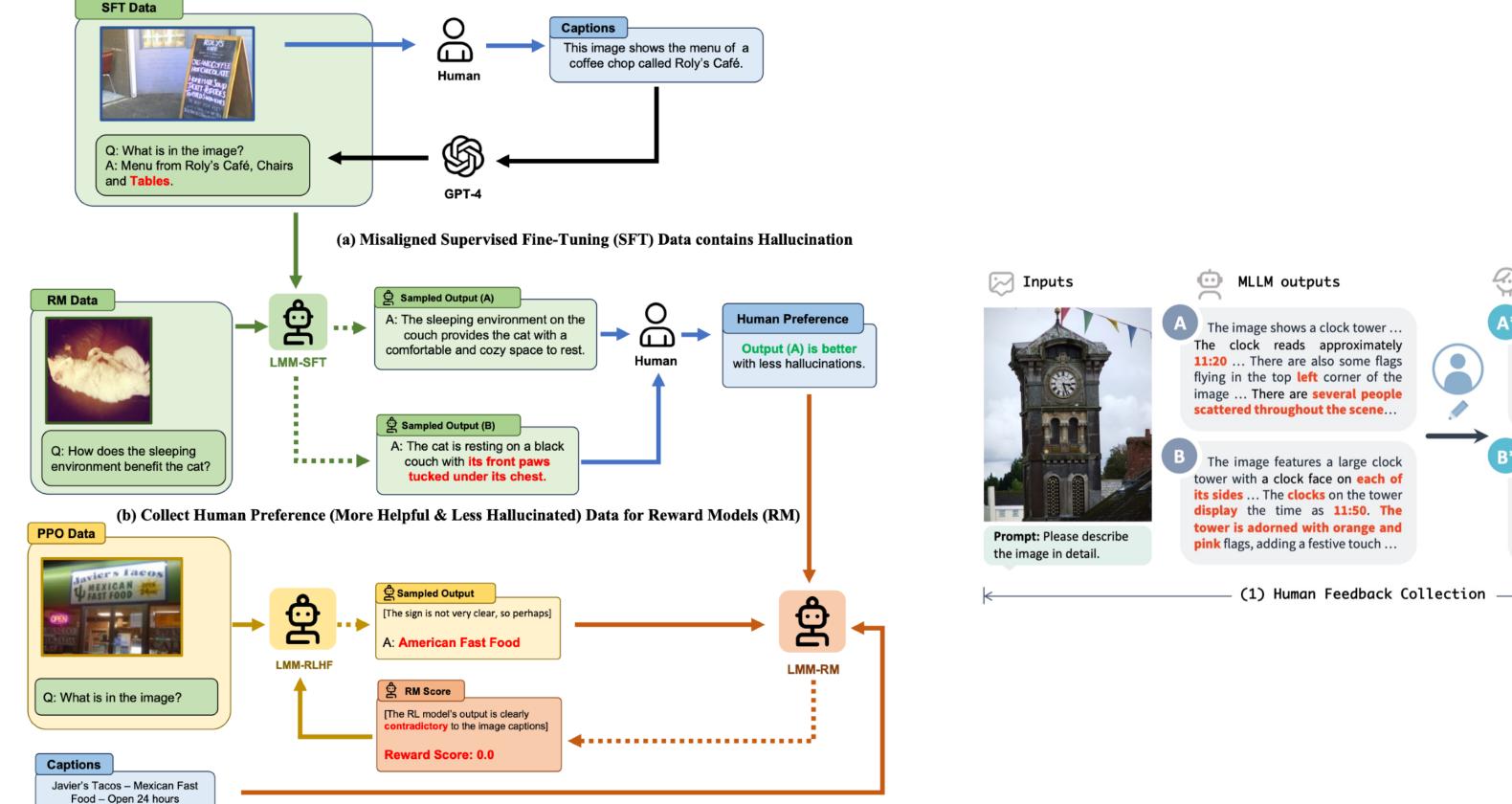
Multimodal ArXiv for LLMs Scientific Understanding

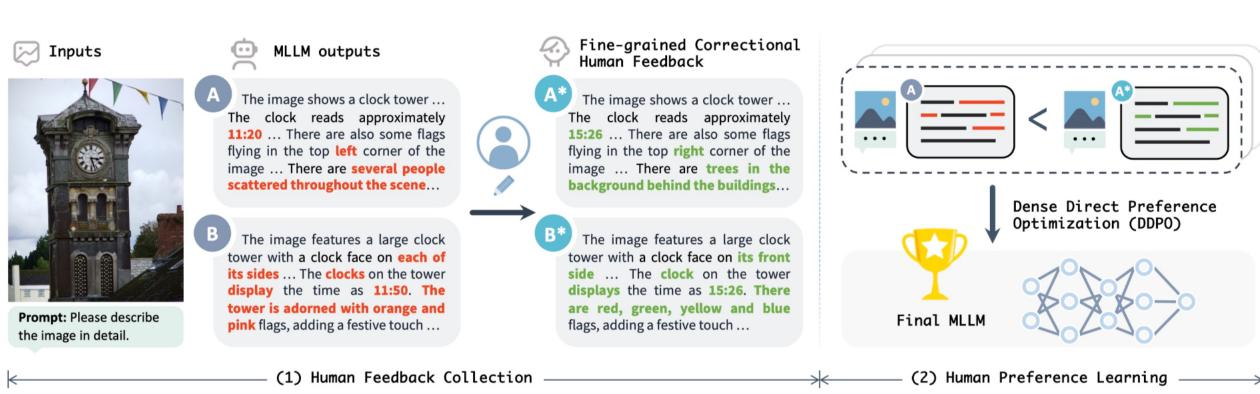


Dataset	Image Number	Paper Number	Image Category	Domain	Real Data
FigCAP (Chen et al., 2020)	219K	N/A	Bar, Line and Pie Charts	N/A	X
SciCap (Yang et al., 2023b)	2.1M	295K	Open-Category	Computer Science and Machine Learning	✓
M-Paper (Hu et al., 2023)	350K	48K	Open-Category	Mainly "Deep Learning"	✓
ArXivCap (Ours)	6.4M	572K	Open-Category	Open-Domain	✓
FigureQA (Kahou et al., 2017)	140K	N/A	Bar, Line and Pie Charts	N/A	X
DVQA (Kafle et al., 2018)	300K	N/A	Bar Charts	N/A	×
ArXivQA (Ours)	32K	16.6K	Open-Category	Open-Domain	✓

Feedback Dataset for LLMs

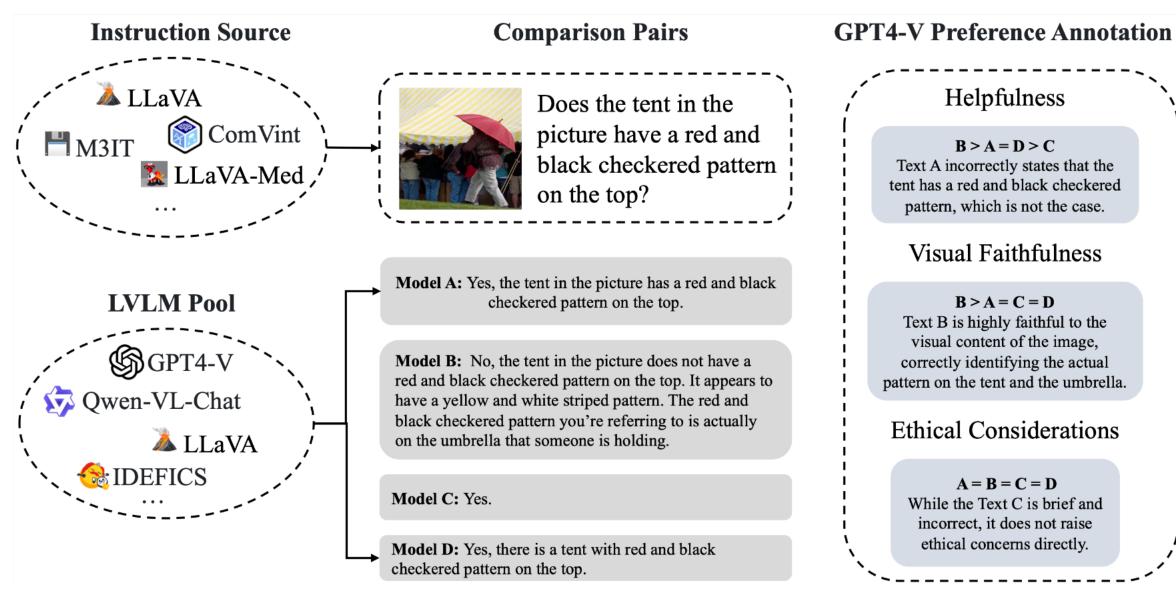
(c) Factually Augmented Reinforcement Learning from Human Feedback (Fact-RLHF)





Aligning Large Multimodal Models with Factually Augmented RLHF RLHF-V: Towards Trustworthy MLLMs via Behavior Alignment from Fine-grained Correctional Human Feedback

VLFeedback: Preference Distillation for LLMs



- We build a GPT-4V annotated vision-language feedback dataset, aithfulness aithfulness consists of 80K instructions decoded by various models,

regarding three aspects.

A Guess of GPT-4V Recipe

- ChatGPT/GPT-4 as backbone LLMs for instruction following & reasoning
- Close-sourced Vision Encoders with 512px with tiling mechanism
 - Note CLIP is also from OpenAl
- Billion Scale (?) ChatGPT paraphrased detailed image-caption pairs for alignment training (inferred from DALLE & SORA practice)
- Diverse vision-language tasks collected for SFT
- OCR pipeline integrated (?)
- Professional alignment team for eliminating bias